HMFS: A Hybrid Message Ferrying Scheme for Clustered Opportunistic Networks

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Abstract

 Opportunistic network is an evolution of MANETs to delivery messages in intermittently connected or completely disconnected wireless networks. Message ferrying is an effective routing mode in opportunistic networks. However, the single message ferry routing scheme leads a much higher delay as the increasing of the network scale, comparing with that in small scale opportunistic networks. It has been proved that multiple message ferries routing scheme can improve the performance of large scale networks, but the problems of synchronization and coordinate between ferries have a bad effect on the routing efficiency. To solve these problems, a Hybrid Message Ferrying Scheme (HMFS) for clustered opportunistic networks is proposed. In HMFS, we divide the communication area into multiple regions based on clustering results and several cross zones containing the regions. A local ferry is deployed in each region to deliver messages in the region, and several global ferries are deployed according to horizontal and vertical zones to communicate among the regions. Moreover, each region has a ferry relay node in it, which is used to orchestrate the local ferry and global ferries. Through the theoretical analysis and simulation results, we can see that HMFS can improve the effect of routing in opportunistic networks in terms of network latency and delivery ratio.

Keywords: message ferrying scheme; opportunistic networks; multiple ferries; network latency; delivery ratio.

1. Introduction

Opportunistic networks are one of the most interesting evolutions of MANETs [1]. In opportunistic networks, wireless links between nodes cannot keep persistent due to node mobility, limited energy and interference. Since the traditional routing protocols are designed on the premise of the established end-to-end communication link from source node to destination node, they fails to deliver messages in opportunistic networks [2]. In opportunistic networks, the paradigm “store-carry-forward” is adopted to replace the using of traditional routing protocols. To communicate in such network environment, messages delivering must rely on the meeting opportunities created by nodes moving, and messages should be carried, till they get the chance to be sent to an intermediate node with a better chance to the destination.

Considering the uncertainty of nodes movement, it is hard to optimize network latency and improve delivery ratio using the “store-carry-forward” routing [3]. Therefore, Message Ferrying (MF) is promoted to deal with this problem. MF is a kind of proactive opportunistic network routing scheme using ferries whose tracks and speeds can be controlled to carry and forward messages. It has been proved that MF scheme can effectively reduce latency and improve delivery ratio in opportunistic networks. Designing the appropriate moving path for ferries is the key to MF scheme.
Authors in [4] propose the basic design of the MF scheme and develop a general framework to classify variations of MF systems. In [5], local ferries are used to improve network performance and connectedness in DTNs and there are several classes of messenger scheduling algorithms which can be used to achieve inter-regional communication in such environments. In HMFRS [6], a message ferry and a ferry access point are deployed in each DTN cluster, in which the ferry access point is utilized to orchestrate the message ferry and the global message ferry which connected the clusters. FGS [7], which exploits multiple local ferries and a global ferry to deliver messages, is proposed to minimize the average message delivery delay. Article [8] proposes cross-regional multiple messengers scheduling method to overcome the shortcoming of messengers scheduling and collaboration in traditional ferry routing.

Compared with small scale opportunistic networks, the single message ferry routing scheme leads a much higher delay as the increasing of the network scale. While multiple ferries routing scheme can solve this problem, but more problems come, such as synchronization and coordinate between ferries. In this paper, a hierarchical ferrying routing scheme for clustered opportunistic networks is proposed, with the name of Hybrid Message Ferrying Scheme (HMFS). In HMFS, we divide the communication area into multiple regions based on clustering results. Local ferry (LF) node is deployed for each cluster to gather messages from ordinary nodes of the same cluster in each region. Global ferry (GF) nodes are deployed to deliver messages crossing different regions. In order to orchestrate the cluster message ferry and global message ferry, ferry relay nodes (FRN) are deployed in every region.

The remainder of paper is organized as follows. In Section 2 we describe the network model and make several assumptions. In Section 3, Hybrid Message Ferrying Scheme is proposed. Section 4 is for the analysis of the delay in HMFS. In Section 5 simulations and results are shown. Section 6 gives the conclusion.

2. Network Model and Assumptions

2.1. Network Model

In HMFS, communication area is divided into \( M = 2m \times 2m \) square regions. Each region contains \( n = N / M \) nodes, a local ferry and a stationary FRN. The two adjacent columns of regions form a vertical zone, and the two adjacent rows form a horizontal zone. Every vertical zone or horizontal zone has one global ferry in it. A local ferry moves in its region and collects message from ordinary nodes in the same regions. It must visit FRN periodically. A global ferry can travel in the particular vertical or horizontal zone. It calls on FRN of the regions in the zone one by one clockwise. It is the duty of global ferries to delivery messages among the regions. The model of a part of HMFS network which contains 16 regions is shown in Figure 1.
To show more details of HMFS, some key elements are defined as follows.

**Region.** Nodes that are distributed close to each other are classified into a cluster, and the area that is chosen to cover the cluster is called a region. In Figure 1, each small square stands for a region. There are 16 regions shown in the part of networks.

**Zone.** There are vertical zones and horizontal zones. Every two adjacent columns of regions form a vertical zone. In this way, the communication area can be cut to several vertical zones. Each one of these vertical zones has no overlap with any other one, and all of them should cover the communication area together. Horizontal zones work the same way as vertical zones. In Figure 1, only one vertical zone and one horizontal zone are signed.

**Intra-message.** Message whose source node and destination node belong to a same region is named intra-message. Intra-message can be send to and receive from the LF of that region.

**Inter-message.** Message whose source node and destination node belong to different regions is named inter-message. To complete the transmission process of inter-message, LFs, FRNs and GFs are all involved.

**Local Ferry.** LFs can only travel in the certain region. They are responsible to delivering both intra-messages and inter-messages. Intra-messages are directly taken from source node to destination node, while inter-messages are sent from the source node to the FRN or from the FRN to the destination node. Local Ferry Route can follow the solution in [9]

**Global Ferry.** GFs, those take charge of inter-message delivering, move clockwise in the certain zone. Inter-messages go from FRN to FRN through GFs.

**Ferry Delay Node.** The FRNs receive, store and forward inter-messages. They relay messages between LFs and GFs as responsibility.

2.3. Assumptions

- For the purpose of analyzing conveniently, some assumptions are made as follows.
- All the nodes are equipped with radio, while LFs and GFs have much longer range radios than ordinary nodes and FRNs.
- Ordinary nodes cannot communicate with each other in any condition.
- LFs and GFs move with a constant speed v.
Ordinary nodes generate the same size messages with a constant data rate.

- The message delay is mainly composed of time when message is stored and carried. The delay caused by message forwarding can be negligible.
- Once a link is built between two nodes, the communication between them cannot disconnect until communication is over.

3. The Design of HMFS

3.1. Route Design

In this section, a relatively short moving path for ferries should be found for the purposes that time can be saved during the messages are carried by ferries. The procedures will be specified respectively.

3.1.1. LF Route Design

There is one LF and one LF only in each region. LF can only move in the region and communicate with nodes in the region. LF should collect messages from nodes and forward them to other nodes. Intra-messages are directly delivered from the source node to the destination node, while inter-messages are delivered with the help of FRN.

In the region, the moving path should be relatively short and ensure that LF can pass every node and FRN, so that the moving period of LF is relatively minimized. We use the method in [7] to deal with this problem. We can get the solutions close to optimal through the method of nearest neighbor procedure, which is shown as follows:

Step 1: Mark all the nodes as unvisited nodes. LF starts at the position of FRN. The node which is nearest to FRN should be chosen as the second node to be visit. Then LF moves to the chosen node and marks it as a visited node.

Step 2: If there is any unvisited node left, LF selects the nearest unvisited node as the next visiting node, then moves to it and marks it as a visited node and repeat this step, else go to Step 3.

Step 3: LF returns to FRN.

3.1.2. GF Route Design

There is one GF and only one GF in each zone (vertical zone or horizontal zone). GF moves in the zone and communicates with FRNs only. GF should collect messages from FRNs and forward them to other FRNs. Only inter-messages can be delivered by GF.

In the zone, the moving path should be relatively short and ensure that FF can pass every FRN, so that the moving period of GF is relatively minimized. This problem is similar to that of LF given above, so the solution is basically the same, which is shown as follows:

Step 1: Mark all FRNs as unvisited FRNs. LF starts at the position of one FRN named starting point. GF choses a nearest unvisited FRN as the next visiting node, then moves to it and marks it as a visited FRN.

Step 2: If there is any unvisited FRN (except the starting one) left, GF selects the nearest unvisited FRN as the next visiting node, then moves to it and marks it as a visited node, else go to Step 3. Repeat step 2.

Step 3: GF goes back to the starting FRN.

3.2. Message Flow

To delivering messages from source node to destination node needs cooperation of LFs, FGs and FRNs. The working process of them is explicated at the view of message flow in this section.
3.2.1. Intra-message Flow

An intra-message \( M_i \) whose destination is node \( j \) is generated in the node \( i \). Node \( i \) and node \( j \) are in the same region, in which region there is \( LF_i \). Firstly, node \( i \) forwards \( M_i \) to \( LF_i \) when \( LF_i \) passes by node \( i \). Secondly, \( LF_i \) stores and carries \( M_i \) until it meets node \( j \). Finally, \( LF_i \) forwards \( M_i \) to node \( j \) when \( LF_i \) passes by node \( j \).

3.2.2. Inter-message Flow in one Zone

An inter-message \( M_{ij} \) whose destination is node \( j \) is generated in the node \( i \). Node \( i \) is in region \( C_i \) in which region there is \( LF_i \) and \( FRN_i \), and node \( j \) is in region \( C_j \) in which region there is \( LF_j \) and \( FRN_j \). They are all in the same zone with the \( GF_k \). Node \( i \) forwards \( M_{ij} \) to \( LF_i \) when \( LF_i \) passes by node \( i \), and \( LF_i \) stores and carries \( M_{ij} \) until it meets \( FRN_i \). \( FRN_i \) gets \( M_{ij} \) and waits for the coming of \( GF_k \). \( GF_k \) delivers \( M_{ij} \) to \( FRN_j \), \( FRN_j \) keeps \( M_{ij} \) to get the chance of forwarding it to \( LF_j \) when \( LF_j \) passes by. Finally, \( LF_j \) sends \( M_{ij} \) to node \( j \) when they meet.

3.2.3. Inter-messages Flow in Different Zones

An inter-message \( M_{ij} \) whose destination is node \( j \) is generated in the node \( i \). Node \( i \) is in region \( C_i \) in which region there is \( LF_i \) and \( FRN_i \), and node \( j \) is in region \( C_j \) in which region there is \( LF_j \) and \( FRN_j \). There is a horizontal zone \( Z_i \) with \( GF_{R_i} \), that contains region \( C_i \) that is vertical zone \( Z_j \) with \( GF_{R_j} \), that contains region \( C_j \). Region \( k \) is the region which is in both zone \( Z_i \) and zone \( Z_j \), and has \( FRN_i \) in it. Firstly, \( M_{ij} \) is collected with \( LF_i \), and sent to \( FRN_i \). Secondly, \( GF_{R_j} \) picks up \( M_{ij} \) at \( FRN_i \) and drops it to \( FRN_j \). Then, \( GF_{R_j} \) picks \( M_{ij} \) at \( FRN_j \) and drops it to \( FRN_k \). Finally, \( M_{ij} \) is delivered from \( FRN_k \) to node \( j \) by \( LF_j \).

3.3. Period Calibrate

In section 3.1, we have found relatively short moving paths for LFs and GFs. However, an inter-message will wait for another GF period if LF cannot deliver it to FRN just before GF leaves. In general, the period of GF is some times longer than that of LFs. Moreover, LFs know the period of GF, so the time when GF arrives at FRN can be calculated. LF serves for a single region, while GFs do with many regions. To minimize the average delay, LF should calibrate its period to fit the period of GF by the way of waiting at FRN. Considering that there are two GFs passing each region, LF should choose the one whose period is closer to an integer multiples of LF’s.

For example, \( LF_k \) in region \( k \) can communicate with \( GF_k \) for the horizontal zone and \( GF_k \) for the vertical zone. \( T_k \), \( T_i \) and \( T_j \) are periods of \( LF_k \), \( GF_i \) and \( GF_j \). Let \( R_k \) be the ratio of \( T_i \) and \( T_k \), and \( R_k \) be the ratio of \( T_j \) and \( T_k \). \( R_i \) and \( R_j \) can be expressed as:

\[
R_i = \frac{T_i}{T_k} \quad (1)
\]

\[
R_j = \frac{T_j}{T_k} \quad (2)
\]

Let \( A_i \) be the decimal part of \( R_i \), \( A_j \) be the decimal part of \( R_j \). \( A_i \) and \( A_j \) can be expressed as:

\[
A_i = R_i - \lfloor R_i \rfloor \quad (3)
\]

\[
A_j = R_j - \lfloor R_j \rfloor \quad (4)
\]

If \( A_i < A_j \), \( LF_i \) should wait for \( A_i T_k \) time to calibrate its period with \( GF_i \), else \( LF_i \) should wait for \( A_j T_k \) time to calibrate its period with \( GF_j \). Figure 2 shows the working arrangement for LF in case \( A_i < A_j \).
Figure 2. Periods Arrangement

4. Analysis of the Delay in HMFS

Based on the common method for analyzing the delay of message ferrying scheme introduced in the HMFRS, this section analyzes the delay with two algorithms compared the single ferry routing and HMFRS in the following three scenarios in which node i and j are located in different positions.

4.1. Node i and j belong to the Same Region

In the single ferry scheme, let $T$ be the period of ferry route, $T^T_{ij}$ be the distance between node i and j. $d_s(i, j)$, delay for the single ferry scheme, is shown as follow.

$$d_s(i, j) = \frac{T}{2} + \frac{T^T_{ij}}{v}$$ (5)

In HMFRS, let $T_p$ be the period of LF for region p, $T^p_{ij}$ be the distance between node i and j. $d_s(i, j)$, delay for HMFRS, is shown as follow.

$$d_s(i, j) = \frac{T_p}{2} + \frac{T^p_{ij}}{v}$$ (6)

In HMFS, $d_s(i, j)$, delay for HMFS, is the same as HMFRS.

$$d_s(i, j) = \frac{T_p}{2} + \frac{T^p_{ij}}{v}$$ (7)

Considering that the averages distance between two nodes in the same region is $l_0$. $T$, $T_p$, $T^T_{ij}$ and $T^p_{ij}$ can be estimated as follows:

$$T = \frac{N_0}{v}$$ (8)

$$T_p = \frac{n^l_0}{v}$$ (9)

$$T^T_{ij} = \frac{1}{N} \sum_{k=1}^{N} kl_0 = \frac{N+1}{2} l_0$$ (10)

$$T^p_{ij} = \frac{1}{n} \sum_{k=1}^{n} kl_0 = \frac{n+1}{2} l_0$$ (11)

Through (5)-(11), we can see that $d_s(i, j) < d_s(i, j) = d_s(i, j)$, which means the delays of HMFRS and HMFS are the same and smaller than that of the single ferry scheme, in the case of node i and node j being in the same region.

4.2. Node i and j belong to Different Regions p and q in the Same Zone

In the condition that node i and j belong to different regions but to the same zone, the delay of the single ferry scheme is the same as that referred in section 4.1.

In HMFRS, the delay is divided into 3 parts $d_p$, $d^*_{ij}$ and $d_q$.

Let $d_p$ be the delivery delay in region p, $l^p_{ij}$ be the distance between node i and FRN$_p$.

$$d_p = \frac{T_p}{2} + \frac{l^p_{ij}}{v}$$ (12)
Let $d'_q$ be the delivery delay between region $p$ and $q$, $T'$ be the period of GF and $I^{T'}_h$ be the distance between $FRN_p$ and $FRN_q$.

\[
d'_q = \frac{T'}{2} + \frac{I^{T'}_h}{v}
\]

Let $d_q$ be the delivery delay in region $q$, $I^{T^*}_v$ be the distance between $FRN_p$ and node $j$.

\[
d_q = \frac{T^*}{2} + \frac{I^{T^*}_v}{v}
\]

The total delivery delay $d(i, j)$ can be shown as follow.

\[
d(i, j) = d_p + d'_q + d_q = \frac{T_p}{2} + \frac{T^*}{2} + \frac{I^{T^*}_q}{v} + \frac{I^{T'}_h + I^{T^*}_v}{v}
\]

In HMFRS, the delay is similar to that of HMFS, but $d'_q$, the delivery delay between region $p$ and $q$, is calculated as follow in which $T_q$ is the period of $GF_q$.

\[
d'_q = \frac{T_q}{2} + \frac{I^{T_q}_h}{v}
\]

So,

\[
d(i, j) = d_p + d'_q + d_q = \frac{T_p}{2} + \frac{T_q}{2} + \frac{I^{T_q}_q}{v} + \frac{I^{T^*}_v + I^{T'}_h}{v}
\]

$T'$, $T^*$, $I^{T'}_h$, $I^{T^*}_v$ and $I^{T^*}_q$ can be estimated as follows:

\[
T' = \frac{M}{v}
\]

\[
T^* = \frac{2mL}{v}
\]

\[
I^{T^*}_v = I^{T^*}_h = \frac{1}{n} \sum_{k=1}^{n} k\ell_0 = \frac{n + 1}{2} \ell_0
\]

\[
I^{T'}_h = \frac{1}{2m} \sum_{k=1}^{2m} k\ell_0 = \frac{2m + 1}{2} \ell_0
\]

Through (5) and (12)-(21), we can see that $d_i(i, j) < d^2(i, j) < d_3(i, j)$, which means the delay of HMFS is the smallest in the three algorithms, in the case of node $i$ and node $j$ being in different regions of the same zone.

### 4.3. Node $i$ and $j$ belong to Different Regions $p$ and $q$ in Zone $x$ and $y$

In the condition that node $i$ and $j$ belong to different regions of different zones, the delay of the single ferry scheme is the same as that referred in section 4.1, the delay of HMFRS is the same as that referred in section 4.2.

In HMFRS, the delay is divided into 4 parts $d_p$, $d_q$, $d_v$ and $d_r$, we choose one of the regions which belongs to both zone $x$ and zone $y$, and call it region $r$.

Let $d_p$ be the delivery delay in region $p$, $I^{T^*}_x$ be the distance between node $i$ and $FRN_p$.

\[
d_p = \frac{T_p}{2} + \frac{I^{T^*}_x}{v}
\]

Let $d_v$ be the delivery delay of $GF_y$ in zone $x$, $T_v$ be the period of $GF_y$, $I^{T^*}_y$ be the distance between $FRN_y$ and $FRN_v$.

\[
d_v = \frac{T_v}{2} + \frac{I^{T^*}_y}{v}
\]

Let $d_r$ be the delivery delay of $GF_y$ in zone $y$, $T_r$ be the period of $GF_y$, $I^{T^*}_r$ be the distance between $FRN_v$ and $FRN_y$.

\[
d_r = \frac{T_r}{2} + \frac{I^{T^*}_r}{v}
\]
Let $d_q$ be the delivery delay in region $q$, $l^T_q$ be the distance between $FRN_q$ and node $j$.

$$d_q = \frac{T_q}{2} + \frac{l^T_q}{v}$$  \hspace{1cm} (25)

The total delivery delay $d_3(i, j)$ can be shown as follow.

$$d_3(i, j) = \frac{T_p + T_x + T_y + T_z}{2} + \frac{l^T_p + l^T_x}{v} + \frac{l^T_y}{v} + \frac{l^T_z}{v}$$ \hspace{1cm} (26)

$T_y$ and $l^T_y$ can be estimated as follows:

$$T_y = \frac{2mL}{v}$$ \hspace{1cm} (27)

$$l^T_y = \frac{1}{2m} \sum_{k=1}^{2m} kL_k = \frac{2m+1}{2} L_0$$ \hspace{1cm} (28)

Similar to the result in section 4.2, we can see that $d_3(i, j) < d_2(i, j) < d_1(i, j)$, which means the delay of HMFS is the smallest in the three algorithms, in the case of node $i$ and node $j$ being in different regions of different zones.

5. Simulation and Results

In order to evaluate the performance of HMFS, HMFS is compared with HMFRS and GFS through the simulations in Opportunistic Networking Environment (ONE) [10]. ONE is developed in the SINDTN and CATDTN projects supported by Nokia Research Center (Finland) and in the TEKES ICTSHOK Future Internet project. ONE has functions such as generating node movement using different movement models, routing messages between nodes with various DTN routing algorithms and sender and receiver types, visualizing both mobility and message passing in real time in its graphical user interface and so on.

The simulations use two key evaluation indexes for opportunistic network, network latency and delivery ratio, and are made under different network constraints in which traffic ratios of inter-message/ intra-message and numbers of regions differ. Each region is a 400m x 400m square area with 16 nodes uniformly distributed in it. Nodes, whose buffer sizes are enough to avoid messages discarded, communicate with the radio transmission range in 20m and the transmission rate of 10Mb/s. Ferries move at the speed of 20m/s with 48-hours simulation duration.

5.1. Impact of Message Traffic Ratio

The communication area is divided into 16 (4 x 4) regions, and nodes generate about 20 intra-messages per second with the average size 1KB. The impact of message traffic ratio is shown in Fig. 3. We can see that HMFS performs better than GFS and HMFRS on both delay and delivery ratio, and gaps grows as the traffic ratio increases. This simulation result proves that HMFS can get better performance in opportunistic networks with more cross-region messages.
5.2. Impact of Region Number

The impact of region number can be seen in Fig. 4.

Nodes generate about 20 intra-messages and 20 inter-messages per second with the average size 1KB. In Fig. 4, we can see the delay and delivery ratio have a considerable influence with increasing of region numbers. HMFS works much better than GFS and HMFRS, and is not so sensitive to the increase as the other two algorithms. This simulation result proves that HMFS can get better performance in large large-scale opportunistic networks.

6. Conclusion

In this paper, we focus on the problems of the message ferrying scheme for clustered opportunistic networks and propose a kind of ferry routing called HMFS. HMFS can reduce latency and improve delivery ratio with region and cross-zone division, through which the path of GF can be shorten greatly. Furthermore, to solve the problems of synchronization and coordinate between ferries, FRN is introduced to orchestrate LF and GF. It can be seen, from both theoretical analysis and simulation results, that HMFS can improve the effect of routing in opportunistic networks in terms of network latency and delivery ratio.
An efficient algorithm is not included in this paper, which can improve the network performance in the single region. This problem should be solved in the future work.

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